Universal Voltage Type with Built-in Amplifier

Compact, universal voltage type with built-in amplifier

■ Features

- •Small and universal voltage type.
- Easy installation with LED indicators on product.
- •Able to set the operation mode by switch. (Light ON/Dark ON)
- •Status and output LED indication
- •Built-in IC photo diode for ambient light and electrical noise.





Please read "Caution for your safety" in operation manual before using.

Specifications

●AC/DC power, Relay contact output

Model		BEN10M-TFR	BEN5M-MFR	BEN3M-PFR	BEN300-DFR		
Sensing t	ype	Transmitted beam	Retroreflective (Standard type)	Retroreflective (with polarizing filter)	Diffuse reflective		
Sensing	distance	10m	(*1) 0.1 ~ 5m	(*1) 0.1 ~ 3m	(*2) 300mm		
Sensing target		Opaque materials of Min. ϕ 16mm	Opaque materials of Min. Ø 60mm		Transparent, Translucent Opaque materials		
Hysteresis					Max. 20% at rated setting distance		
Response time		Max. 20ms					
Power sup	oply	24-240V	AC ±10% 50/60Hz, 24-2	40VDC ±10% (Ripple P-P:	Max. 10%)		
Power cor	nsumption	Max. 4VA					
Light source		Infrared LED (modulated) Red LED (Modulated: 660nm) Infrare		Infrared LED (modulated)			
Sensitivity adjustment		——— Adjuster					
Operation mode		Light ON / Dark ON mode selectable					
Control output		Relay contact output (Contact capacity: 30VDC 3A resistive load, 250VAC 3A resistive load, Relay contact composition: 1c)					
Relay life cycle		Mechanically: Min. 50,000,000, Electrically: Min. 100,000					
Light receiving element		Built-in IC type photo diode					
Indicator		Operation indicator : Orange, Stable indicator : Green (The orange lamp on Emitter of transmitted beam type is for power indication)					
Connection		Outgoing cable					
Insulation resistance		Min. 20MΩ (at 500VDC mega)					
Noise strength		$\pm 1{,}000\mathrm{V}$ the square wave noise(pulse width:1 μ s) by the noise simulator					
Dielectric strength		1000VAC 50/60Hz for 1minute					
Vibration	Mechanical	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours					
Vibration	Malfunction	1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 10 minutes					
Shock	Mechanical	500m/s ² (50G) in X, Y, Z directions for 3 times					
	Malfunction	100m/s² (10G) in X, Y, Z directions for 3 times					
Ambient illumination		Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x					
Ambient temperature		-20 ~ +65℃ (at non-freezing status), Storage:-25 ~ +70℃					
Ambient humidity		35 ~ 85%RH, Storage : 35 ~ 85%RH					
Material		Case: ABS, Lens cover: Acrylic, Lens: Acrylic					
Protection		IP50(IEC standard)					
Cable		∅ 6.0mm, 5P, Length : 2m					
Accessory	Individual		Reflector (MS-2)	, Adjustment driver	Adjustment driver		
, (CCC3301)	Common		Fixing bracke	t, Bolts, Nuts			
Unit weight		Approx. 354g	Appro	x. 208g	Approx. 195g		

^{(★1)}**It is mounting distance between sensor and reflector MS-2 and it is same when MS-4 is used. It is detectable under 0.1m. ****(★2)** It is for Non-glossy white paper(100×100mm).

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(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

•DC power, Solid state output

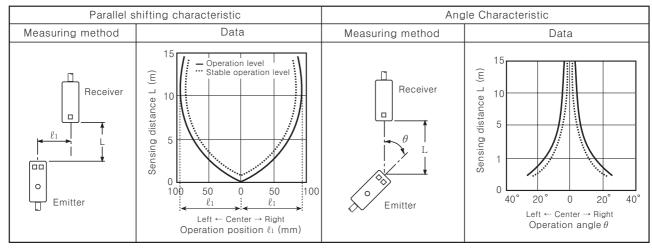
Model		BEN10M-TDT	BEN5M-MDT	BEN3M-PDT	BEN300-DDT	
Sensing typ	pe	Transmitted beam	Retroreflective	Retroreflective (with polarizing filter)	Diffuse reflective	
Sensing di	stance	10m	(*1) 0.1 ~ 5m	(*1) 0.1 ~ 3m	(*2) 300mm	
Sensing target		Opaque materials of Min. ∮16mm	Opaque materials of Min. ∅60mm		Transparent, Translucent, Opaque materials	
Hysteresis					Max. 20% at sensing distance	
Response time		Max. 1ms				
Power supp	ply	12-24VDC ±10% (Ripple P-P : Max. 10%)				
Power con:	sumption	Max. 40mA				
Light source		Infrared LEI	ED(modulated) Red LED (modulated, 660nm)		Infrared LED (modulated)	
Sensitivity	adjustment	———— Adjuster				
Operation mode		Light ON / Dark ON mode selectable				
Control output		●NPN/PNP output simultaneously • PNP open collector output ☞ Load voltage:Max. 30VDC, Load current:Max. 200mA, Residual voltage:Max. 1V • NPN open collector output ☞ Output voltage:Min. (Power supply -2.5)V, Load current:Max. 200mA				
Protection circuit		Reverse polarity protection, Short-circuit protection				
Light receiving element		Built-in IC type photo diode				
Indicator		Operation indicator : Orange, Stable indicator : Green (The orange lamp on Emitter of transmitted beam type is for power indicator)				
Connection		Outgoing cable				
Insulation resistance		Min. 20MΩ (at 500VDC mega)				
Noise strength		$\pm 240 \text{V}$ the square wave noise(pulse width:1 μ s) by the noise simulator				
Dielectric strength		1000VAC 50/60Hz for 1minute				
Vibration		1.5mm amplitude at frequency of 10 ~ 55Hz in each of X, Y, Z directions for 2 hours				
Shock		500m/s ² (50G) in X, Y, Z directions for 3 times				
Ambient illumination		Sunlight: Max. 11,000/x, Incandescent lamp: Max. 3,000/x				
Ambient temperature		-20 ~ +55 ℃ (at non-freezing status), Storage : -25 ~ +70 ℃				
Ambient humidity		35 ~ 85%RH, Storage : 35 ~ 85%RH				
Protection		IP50 (IEC standard)				
Material		Case: ABS, Lens cover: Acrylic, Lens: Acrylic				
Cable		∅ 6.0mm, 4P, Length : 2m				
Accessory	Individual		Reflector (MS-2)	Adjustment driver	Adjustment driver	
	Common		Fixing bracket	, Bolts, Nuts		
Approval		C€				
Unit weight		Approx. 342g	Appro	x. 200g	Approx. 187g	
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 $^{**(\}star 1)$ It is mounting distance between sensor and reflector MS-2 and it is same when MS-4 is used. It is detectable under 0.1m. $**(\star 2)$ It is for Non-glossy white paper(100×100mm).

■ Feature data

©Transmitted beam

●BEN10M-TFR ●BEN10M-TDT



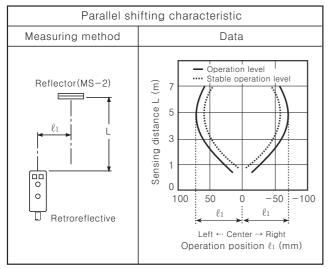
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Universal Voltage Type with Built-in Amplifier

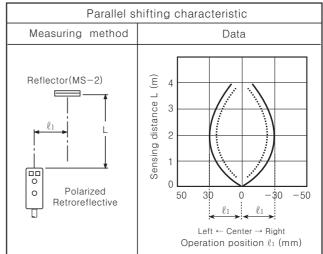
■ Feature data

Retroreflective

●BEN5M-MFR ●BEN5M-MDT



○Polarized retroreflective●BEN3M-PFR ●BEN3M-PDT



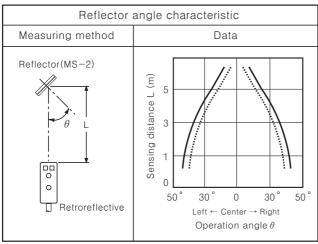
●BEN5M-MFR ●BEN5M-MDT

Sensor angle characteristic				
Measuring method	Data			
Reflector(MS-2) Retroreflective	Sensing distance L (m) 2 sons 10° S° 0 5° 10° Left ← Center → Right Operation angle θ			

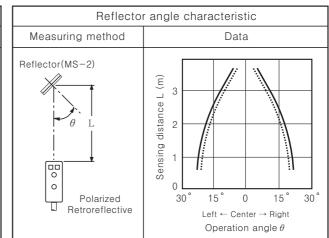
●BEN3M-PFR ●BEN3M-PDT

Sensor angle characteristic				
Measuring method	Data			
Reflector(MS-2) Polarized Retroreflective	(m) 3 2 2 2 2 2 3 10° 5° 0 5° 10° 10° Left ← Center → Right Operation angle θ			

●BEN5M-MFR ●BEN5M-MDT



●BEN3M-PFR ●BEN3M-PDT



(A) Counter

(B) Timer

(C) Temp. controller

(D) Power controller

(E) Panel meter

(F) Tacho/ Speed/ Pulse meter

(G) Display

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

(L) Pressure sensor

(M) Rotary encoder

(N) Stepping motor & Driver & Controller

(O) Graphic panel

(P) Field network device

(Q) Production stoppage models & replacement

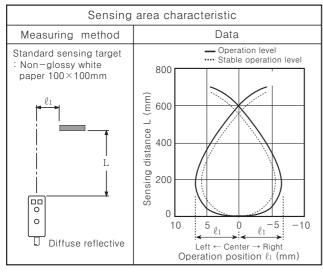
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BEN Series

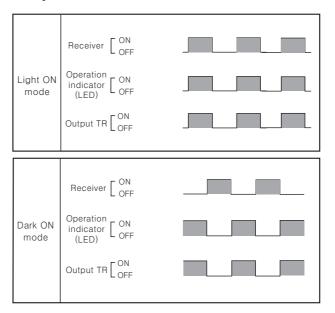
■ Feature data

ODiffuse reflective

●BEN300-DFR ●BEN300-DDT

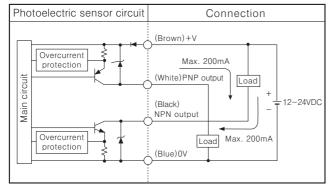


Operation mode

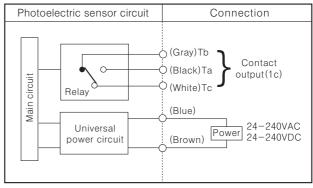


■Control output diagram

●DC voltage(NPN/PNP synchronous output)



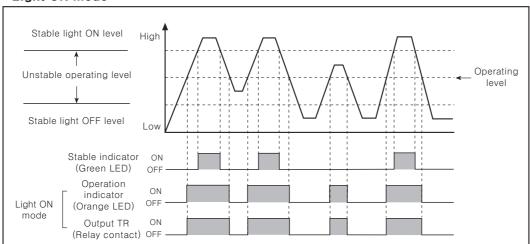
Universal voltage(Relay contact output)



^{*}In case of product with the output protection device, if terminals of control output are short circuited or overcurrent condition is existed, the control output will turn off due to protection circuit.

Operation mode and timing chart

Light ON mode

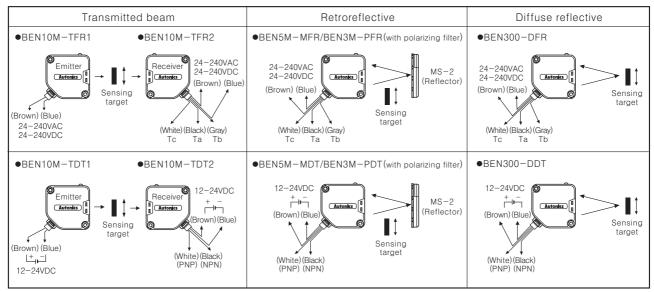


^{*}The waveform of output TR and operation indicator are the state of operation for Light ON mode, but in case of Dark ON mode, it operates as reverse against Light ON mode.

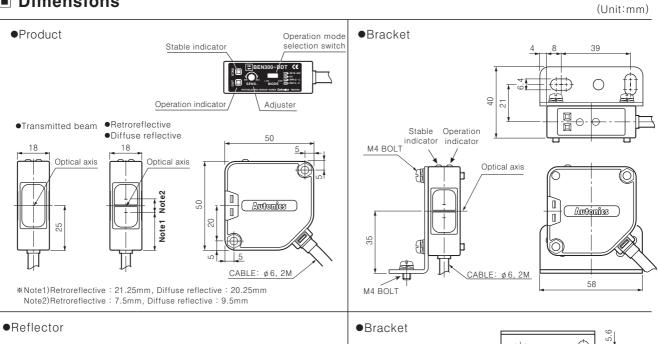
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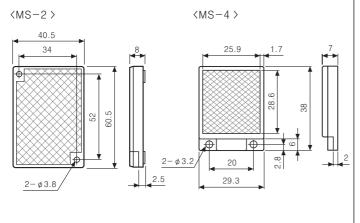
Universal Voltage Type with Built-in Amplifier

Connections



Dimensions





21 12 39 58 20 60 R2.25 Counter

(R) Timer

Temp. controller

(D) Power controller

(E) Panel meter

Tacho/ Speed/ Pulse meter

Display unit

(H) Sensor controller

(I) Switching power supply

(J) Proximity sensor

(K) Photo electric sensor

Pressure

(M) encoder

(N) Stepping motor & Driver & Controller

Graphic panel

Field device

(Q) Production stoppage models &

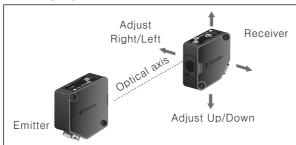
Autonics K - 42

BEN Series

■ Mounting and sensitivity adjustment

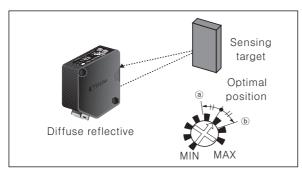
©Transmitted beam type

- 1. Supply the power to the photoelectric sensor, after set the emitter and the receiver facing each other.
- 2. Set the receiver in the middle of the operation range of indicator adjusting the receiver or the emitter right and left, up and down.
- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.
- *If the sensing target is translucent body or smaller than \$\phi\$ 16mm, it can be missed by sensor cause light passed.



ODiffuse reflective type

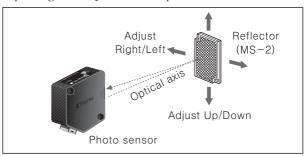
- 1. Adjust sensitivity regarding the effectiveness of behind object or mounting side.
- 2. Set the target at a position to be detected by the beam, then turn the adjuster until position ⓐ in the middle of the operation range of indicator from min. position of the adjuster.
- 3. Take the target out of the sensing area, then turn the adjuster until position (b) where the indicator turns on. If the indicator does not turn on, Max. position is position (b).
- 4. Set the adjuster at the middle of two switching position (a), (b).
- *The sensing distance indicated on specification chart is against 100×100mm of non-glossy white paper. Be sure that it can be different by size, surface and gloss of target.



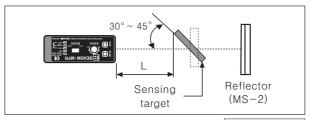
©Retroreflective type

- Supply the power, after set the photoelectric sensor and the reflector (MS-2) facing each other.
- 2. Set the Photoelectric sensor in the middle of the position in the middle of the operation range of indicator adjusting the reflector or the sensor right and left, up and down.

- 3. Adjust up and down direction as the same.
- 4. After adjustment, check the stability of operation putting the object at the optical axis.



- *If use more than 2 photoelectric sensors in parallel, the space between them should be more than 30cm.
- **If reflectance of target is higher than non-glossy white paper, it might cause malfunction by reflection from the target when thr target is near to photoelectric sensor. Therefore put enough space between the target and photoelectric sensor or the surface of target should be installed at an angle of 30 °~45 °against optical axis.
 - (When detecting target with high reflectance near by, photoelectric sensing with the polarizing filter should be used.)
- **Sensitivity adjustment : Please see the diffuse reflective type.

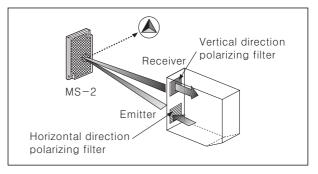


※If the mounting place is too small, please use MS−4 instead of MS−2 for same sensing distance.



©Retroreflective type(With polarizing filter)

The light passed through the polarizing filter of emitter reaches to MS-2 converting as horizontal direction, it reaches to photodetector through the filter of receiver converting as vertical by MS-2 function. Even it can detect normal mirror.



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